

compatible mappings on a 2-Metric Space

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Abstract: The aim of the present paper is to obtain i) a common fixed point theorem for compatible mappings by using the concept of asymptotic regularity and ii) a common fixed point theorem using the concept of joint reciprocal continuity in 2- metric spaces. A supporting example is also given.

Keywords: common fixed point , Compatible mappings and asymptotic regularity.

Mathematical subject Classification : 47 H 10, 54H25

1. Introduction : Gähler[2] introduced the concept of 2-metric space as a natural generalization of a metric space. Some fixed point theorems in 2-metric spaces are obtained in Iseki[3],Rhoades[5] and Jungck[4]. Gähler[2] introduced the notions of reciprocal continuity and asymptotic regularity for a pair of self maps on a 2-metric space. Using the above concepts Badshah and Gopal Meena[1] proved a fixed point theorem for a pair of self-maps on a 2-metric space using asymptotic regularity.

The present paper is a generalization of a result of Badshah and Gopal Meena([1],Theorem 2).

In this paper, we obtain i) a common fixed point theorem (Th. (2.1)) for compatible mappings by using the concept of asymptotic regularity and ii) a common fixed point theorem (Th. (2.6)) using the concept of joint reciprocal continuity. We start with some definitions.

Definition 1.1 (Gähler[2]): Let X be a non-empty set with real valued function $d: X^3 \rightarrow R$ satisfying :

- i) For two distinct points x, y in X , there exists z in X such that $d(x, y, z) \neq 0$
- ii) $d(x, y, z) = 0$ only if at least two of x, y and z are equal
- iii) $d(x, y, z) = d(x, z, y) = d(y, z, x)$ and
- iv) $d(x, y, z) \leq d(x, y, u) + d(x, u, z) + d(u, y, z)$ for all x, y, z, u in X .

The function d is called a 2-metric on X and the pair (X, d) is called a 2-metric space.

Definition 1.2 (Gähler[2]) : Let (X, d) be a 2-metric space .

- i) A sequence $\{x_n\}$ is said to be convergent to a point x in X if $d(x_n, x, a) = 0, \forall a \in X$.
- ii) A sequence $\{x_n\}$ is said to be a Cauchy sequence in X if $d(x_m, x_n, a) = 0, \forall a \in X$.
- iii) A 2-metric space (X, d) is said to be complete if every Cauchy sequence in X converges to a point in X .

Note: i) In a 2-metric space (X, d) , $d: X^3 \rightarrow R$ is continuous if

$$x_n \rightarrow x, y_n \rightarrow y \text{ implies } d(x_n, y_n, a) \rightarrow d(x, y, a), \forall a \in X \text{ for } n \rightarrow \infty.$$

- ii) If $x_n \rightarrow x$ and $x_n \rightarrow y$ as $n \rightarrow \infty$ then $x = y$.

Definition 1.3 (Gähler[2]): For self-mappings, S and T of a 2-metric space (X, d) , the pair (S, T) is called reciprocally continuous if $d(STx_n, Sx, a) = 0 = \forall a \in X$, whenever $\{x_n\}$ is a sequence in X such that $Sx_n = Tx_n = x$, for some $x \in X$.

Definition 1.4 (Gähler[2]): For self-mappings, S and T of a 2-metric space (X, d)

- i) A sequence $\{x_n\}$ in X is called asymptotically regular with respect to the pair (S, T) if $d(Sx_n, Tx_n, a) = 0 \forall a \in X$.
- ii) The pair (S, T) is called compatible if $d(STx_n, TSx_n, a) = 0 \forall a \in X$, whenever $\{x_n\}$ is a sequence in X such that $Sx_n = Tx_n = x$, for some $x \in X$.

Definition 1.5: Suppose P, S and T are self maps on a 2-metric space (X, d) . The pair (S, T) is said to be joint reciprocal continuous with respect to P if there exists a sequence $\{x_n\}$ in X such that $Sx_n = Tx_n$ and $d(PSx_n, SPx_n, a) = 0$ and $d(PTx_n, TPx_n, a) = 0 \forall a \in X$.

Note : If $\{x_n\}$ is a sequence in X such that $Sx_n = Tx_n$

and (P, S) and (P, T) are compatible then (S, T) is jointly reciprocally continuous with respect to P .

Notation: $\Phi = \{\varphi: [0, \infty) \rightarrow [0, \infty), \varphi \text{ is continuous and } \varphi(t) < t \forall t > 0\}$.

2. Main Results

We begin with our first main result, from this we obtain corollaries of the main result and finally show that the result of Badshah and Gopal Meena[1] follows as a corollary.

Theorem 2.1: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \varphi (\{ d(Py, Ty, a)(1 + d(Px, Sx, a)), d(Px, Sx, a)(1 +$$

$\forall x, y, a \in X$ and for some $\varphi \in \Phi$,

ii) the pair (P, S) and (P, T) are compatible

iii) there exists a sequence $\{x_n\}$ which is asymptotically regular with respect (P, S) and (P, T)

iv) S and T are continuous v) d is continuous.

Then P, S and T have a unique common fixed point in X .

Proof: Let $\{x_n\}$ be a sequence in X satisfying condition (iii).

By taking $x = x_n$ and $y = x_m$ in (i), we obtain

$$d(Px_n, Px_m, a) \leq \varphi \{ d(Px_m, Tx_m, a)(1 + d(Px_n, Sx_n, a)), d(Px_n, Sx_n, a)(1 + d(Px_m, Tx_m, a)) \} \quad (2.1.1)$$

On letting $n \rightarrow \infty$ and using condition (iii), we get

$$d(Px_n, Px_m, a) = 0 \quad \forall a \in X.$$

This implies that the sequence $\{Px_n\}$ is a Cauchy sequence in X , since X is complete with respect to 2-metric d .

This implies

$$Px_n \rightarrow z, \text{ for some } z \in X. \quad (2.1.2)$$

Now

$$d(Sx_n, z, a) \leq d(Sx_n, z, Px_n) + d(Sx_n, Px_n, a) + d(Px_n, z, a)$$

On letting $n \rightarrow \infty$, using condition (iii) and equation (2.1.2), we get

$$d(Sx_n, z, a) = 0 \quad \forall a \in X.$$

$$\text{This implies } Sx_n \rightarrow z \text{ in } X. \quad (2.1.3)$$

Similarly we can obtain

$$Tx_n \rightarrow z \text{ in } X. \quad (2.1.4)$$

Since we can write

$$d(PSx_n, Sz, a) \leq d(PSx_n, Sz, SPx_n) + d(PSx_n, SPx_n, a) + d(SPx_n, Sz, a)$$

On letting $n \rightarrow \infty$, using the conditions (ii), (iv) and (v), we get

$$d(PSx_n, Sz, a) = 0 \quad \forall a \in X,$$

($\because Px_n \rightarrow z$ and S is continuous implies $SPx_n \rightarrow Sz$)

$$\text{This implies } PSx_n \rightarrow Sz. \quad (2.1.5)$$

$$\text{Similarly we can prove } PTx_n \rightarrow Tz. \quad (2.1.6)$$

By taking $x = Sx_n$ and $y = Tx_n$ in (i), we obtain

$$d(PSx_n, PTx_n, a) \leq \varphi(\max\{d(PTx_n, TTx_n, a)(1 + d(PSx_n, SSx_n, a)), \\ d(PSx_n, SSx_n, a)(1 + d(PTx_n, TTx_n, a))\}) \quad (2.1.7)$$

From condition (iv) we have S and T are continuous, applying continuity of S and T in (2.1.3) and (2.1.4), we get

$$SSx_n \rightarrow Sz, TTx_n \rightarrow Tz \text{ and } STx_n \rightarrow Sz \quad (2.1.8)$$

On letting $n \rightarrow \infty$ in (2.1.7), using (2.1.5), (2.1.6), (2.1.8) and condition (v), we get

$$d(Tz, Sz, a) = 0, \quad \forall a \in X.$$

$$\text{This implies } Tz = Sz. \quad (2.1.9)$$

Similarly by taking $x = Tx_n$ and $y = z$ in (i), we get

$$d(PTx_n, Pz, a) \leq \varphi(\{d(Pz, Tz, a)(1 + d(PTx_n, STx_n, a)), d(PTx_n, STx_n, a)(1 + d(Pz, Tz, a))\})$$

On letting $n \rightarrow \infty$, using ((2.1.7), (2.1.8), (2.1.9) and condition (v), we get $d(Tz, Pz, a) = 0, \forall a \in X$.

$$\text{This implies } Tz = Pz. \quad (2.1.10)$$

$$\text{Therefore } Sz = Tz = Pz. \quad (2.1.11)$$

By taking $x = x_n$ and $y = z$ in (i), we get

$$d(Px_n, Pz, a) \leq \{d(Pz, Tz, a)(1 + d(Px_n, Sx_n, a)), d(Px_n, Sx_n, a)(1 + d(Pz, Tz, a))\}$$

On letting $n \rightarrow \infty$ and using (2.1.2),(2.1.3),(2.1.11) and condition(iv), we get

$$d(z, Pz, a) = 0, \forall a \in X. \text{ This implies } Pz = z.$$

Therefore z is a fixed point of P . Hence z is a common fixed point of S, T and P in X .

Suppose if x is common fixed point of S, T and P in X . Then it can be easily proved that $x = z$. Hence z is a unique common fixed point of S, T and P in X .

Now we have the following corollaries of theorem 2.1.

Corollary 2.2: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \varphi\{d(Py, Ty, a)(1 + d(Px, Sx, a)), d(Px, Sx, a)(1 + d(Py, Ty, a), d(Px, Sx, a), d(Py, Sy, a)\}$$

$\forall x, y, a \in X$ and for some $\varphi \in \Phi$, and also satisfying condition (ii), (iii), (iv) and (v) of theorem 2.1.

Then P, S and T have a unique common fixed point in X .

Corollary 2.3 : Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \lambda\{d(Py, Ty, a)(1 + d(Px, Sx, a)), d(Px, Sx, a)(1 + d(Py, Ty, a), d(Px, Sx, a), d(Py, Sy, a)\}$$

$\forall x, y, a \in X, 0 < \lambda < 1$ and also satisfying condition (ii), (iii), (iv) and (v) of theorem 2.1.

Then P, S and T have a unique common fixed point in X .

Corollary 2.4: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \alpha\{d(Py, Ty, a)(1 + d(Px, Sx, a)), d(Px, Sx, a)(1 + d(Py, Ty, a)\} + \beta \max\{d(Px, Sx, a), d(Py, Sy, a)\}$$

$\forall x, y, a \in X, \alpha$ and β are non – negative numbers such that $\alpha + \beta < 2$ and

also satisfying condition (ii), (iii), (iv) and (v) of theorem 2.1.

Then P, S and T have a unique common fixed point in X .

Corollary 2.5: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \alpha\beta\{d(Px, Sx, a) + d(Py, Sy, a)\}$$

$\forall x, y, a \in X, \alpha$ and β are non – negative numbers such that $\alpha + \beta < 2$ and also satisfying condition (ii), (iii), (iv) and (v) of theorem 2.1.

Then P, S and T have a unique common fixed point in X .

The following result due to Badshah and Gopal Meena[1] is a corollary of the above result.

Corollary 2.6 (Badshah and Gopal Meena[1],Theorem 2): Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \alpha \frac{d(Py, Ty, a)(1+d(Px, Sx, a))}{1+d(Sx, Ty, a)} + \beta \{d(Px, Sx, a) + d(Py, Sy, a)\}$$

$\forall x, y, a \in X$, α and β are non – negative numbers such that $\alpha + \beta < 2$,

and also satisfying condition (ii), (iii), (iv) and (v) of theorem 2.1.

Then P, S and T have a unique common fixed point in X .

Now we state our second main result which uses the concept of joint reciprocal continuity.

Theorem 2.7: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying:

$$i) d(Px, Py, a) \leq \varphi(\{d(Py, Ty, a)(2 + d(Px, Sx, a)), d(Px, Sx, a)(2 + d(Py, Ty, a))\})$$

$\forall x, y, a \in X$ and for some $\varphi \in \Phi$,

ii) S and T are continuous

iii) d is continuous.

iv) (S, T) is joint reciprocal continuous w. r. t. P in X .

Then P, S and T have a unique common fixed point in X .

Proof: From condition (iv) there exists a sequence $\{x_n\}$ in X such that

$$Sx_n = Px_n = Tx_n = z \text{ for some } z \in X \quad (2.5.1)$$

and

$$d(PSx_n, SPx_n, a) = 0 = d(PTx_n, TPx_n, a) \forall a \in X \quad (2.5.2)$$

Applying condition (ii) in equation (2.5.1) and using this in the equation (2.5.2), we get

$$PSx_n \rightarrow Sz \text{ and } PTx_n \rightarrow Tz. \quad (2.5.3)$$

By taking $x = Sx_n$, $y = Tx_n$ in (i) and letting $n \rightarrow \infty$, using conditions (ii), (iii) and (2.5.2) and (2.5.3), we get $Sz = Tz$. (as derived in theorem 2.1)

Similarly taking $x = Tx_n$ and $y = z$ in (i) and letting $n \rightarrow \infty$, we get

$Pz = Tz$ (as derived in theorem 2.1). Therefore $Sz = Pz = Tz$.

Taking $x = x_n$ and $y = z$ in (i) and letting $n \rightarrow \infty$, we get $z = Pz$.

This is z is a fixed point of P . Hence z is a common fixed point of S, T and P in X .

Suppose if x is common fixed point of S, T and P in X . Then it can be easily proved that $x = z$. Hence z is a unique common fixed point of S, T and P in X .

Now we have the following corollaries of theorem 2.6.

Corollary 2.8 : Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying: condition (i) of corollary (2.2) and conditions (ii), (iii) and (iv) of theorem (2.7).

Corollary 2.9: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying: condition (i) of corollary (2.3) and conditions (ii), (iii) and (iv) of theorem (2.7).

Then P, S and T have a unique common fixed point in X .

Corollary 2.10: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying: conditions (i) of corollary(2.4) and also conditions (ii), (iii) and (iv) of theorem (2.6).

Then P, S and T have a unique common fixed point in X .

Corollary 2.11: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying: conditions (i) of corollary (2.5) and also conditions (ii), (iii) and (iv) of theorem (2.7).

. Then P, S and T have a unique common fixed point in X .

Corollary 2.12: Let P, S and T be self-mappings of a complete 2-metric space (X, d) satisfying: conditions (i) of corollary 2.7 and also the conditions (ii), (iii) and (iv) of theorem (2.7).

Then P, S and T have a unique common fixed point in X .

Example 2.11:

Let $X = R \times R$ for $A, B \in X$, denote the Euclidean distance A and B by $|A - B|$.

Define $d: X^3 \rightarrow R$ by $d(A, B, C) = \{|A - B|, |B - C|, |C - A|\}$. Then (X, d)

is a complete 2-metric space. Let $A_0 \in X$. Define the mappings

P, S and T on X as $P(A) = A_0 \forall A \in X$ and $S = T = I$.

Define $\varphi(t) = \eta t, 1 < \eta < 12$ then $\varphi \in \Phi$. Then P, S and T satisfy all

the properties of Theorem 2.1 and Theorem 2.7 and A_0 is the unique common

fixed point of P, S and T in X .

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