

A Study on Exact Solution of an Integrable Generalized Hirota-Satsuma Equation of (2+1)-Dimensions Via $\exp(-\Phi(\xi))$ -Expansion Method

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Abstract:

In this paper, we have studied (2+1) Dimensional integrable generalized Hirota- Satsuma (gHS) equation to create abundant exact solution using $\exp(-\Phi(\xi))$ -expansion method. As a result, we get some exact solutions in-terms of trigonometric, hyperbolic and logarithmic functions with various structures. Finally, we presented some of the obtained solution with graphical illustration via symbolic computation.

Keywords —Hirota- Satsuma equation, $\exp(-\Phi(\xi))$ -expansion method, traveling wave, exact solution.

I. INTRODUCTION

Mathematical modeling of dynamical processes in a great variety of natural phenomena leads in general to NPDEs. There is a particular class of solutions for these nonlinear equations that are of considerable interest. They are the traveling wave solutions such a wave is special solution of the governing equations, that may be localized or periodic, which does not change its shape and which propagates at constant speed. In the case of linear equations the profile is usually arbitrary. In contrast a nonlinear equation will normally determine a restricted class of profiles, as the result of a balance between nonlinearity and dissipation. In recent years, the exact solutions of NPDEs have been investigated by many researchers (see for example [1-21]) who are interested in nonlinear physical phenomena which exist in all fields including either the scientific works or engineering fields.

The main purpose of this paper is to demonstrate the $\exp(-\Phi(\xi))$ -expansion method for finding the exact traveling wave solutions of an integrable generalized Hirota- Satsuma equation [13].

II. METHODOLOGY

In this section, we will discuss about $\exp(-\Phi(\xi))$ -expansion method step by step.

Step 1. Firstly, we consider a NLPDE with three independent variables x , y and t as

$$\rho(u, u_t, u_x, u_y, u_{tt}, u_{xx}, u_{yy}, \dots) = 0, \quad (2.1)$$

where $u(\xi) = u(x, y, t)$ is an unknown function, ρ is a polynomial of $u(x, y, t)$ and involving the nonlinear terms and highest order partial derivatives.

Step 2. Combining the independent variables x, y and t into one variables, $\xi = x + y - wt$, we suppose that,

$$u = u(x, y, t), \xi = x + y - wt, u = u(\xi), u(x, y, t) = u(\xi). \tag{2.2}$$

The traveling wave transformation Eq. (2.2) permits us to reduce Eq. (2.1) to the following ordinary differential equation:

$$\wp(u, u', u'', u''' \dots) = 0, \tag{2.3}$$

where \wp is a polynomial in $u(\xi)$ and its derivatives

whereas $u'(\xi) = \frac{du}{d\xi}, u''(\xi) = \frac{d^2u}{d\xi^2}, u'''(\xi) = \frac{d^3u}{d\xi^3}$ and

so on.

Step 3. For this method, suppose the solutions of Eq. (2.3) are as follows:

$$u(\xi) = \sum_{j=0}^m B_j (\exp(-\phi(\xi)))^j. \tag{2.4}$$

where B_j ($0 \leq j \leq m$) are constants to be determined, such that $B_m \neq 0$, and $\phi = \phi(\xi)$ satisfies the following ODE.

$$\phi'(\xi) = \exp(-\phi(\xi)) + \mu \exp(\phi(\xi)) + \lambda \tag{2.5}$$

Eq. (2.5) gives the following solutions:

When $\lambda^2 - 4\mu > 0, \mu \neq 0$,

$$\phi(\xi) = \ln \left\{ \frac{1}{2\mu} \left(-\sqrt{\lambda^2 - 4\mu} \tanh \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} (\xi + \kappa) \right) - \lambda \right) \right\}, \tag{2.6}$$

$$\phi(\xi) = \ln \left\{ \frac{1}{2\mu} \left(-\sqrt{\lambda^2 - 4\mu} \coth \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} (\xi + \kappa) \right) - \lambda \right) \right\}, \tag{2.7}$$

When $\lambda^2 - 4\mu < 0, \mu \neq 0$,

$$\phi(\xi) = \ln \left\{ \frac{1}{2\mu} \left(-\sqrt{4\mu - \lambda^2} \tan \left(\frac{\sqrt{4\mu - \lambda^2}}{2} (\xi + \kappa) \right) - \lambda \right) \right\}, \tag{2.8}$$

$$\phi(\xi) = \ln \left\{ \frac{1}{2\mu} \left(-\sqrt{4\mu - \lambda^2} \cot \left(\frac{\sqrt{4\mu - \lambda^2}}{2} (\xi + \kappa) \right) - \lambda \right) \right\}, \tag{2.9}$$

When $\lambda^2 - 4\mu > 0, \mu = 0, \lambda \neq 0$,

$$\phi(\xi) = \ln \left(\frac{\lambda}{\exp(\lambda(\xi + \kappa)) - 1} \right), \tag{2.10}$$

When $\lambda^2 - 4\mu = 0, \mu \neq 0, \lambda \neq 0$,

$$\phi(\xi) = \ln \left(\frac{2(\lambda(\xi + \kappa) + 2)}{\lambda^2(\xi + \kappa)} \right), \tag{2.11}$$

When $\lambda^2 - 4\mu = 0, \mu = 0, \lambda = 0$,

$$\phi(\xi) = \ln(\xi + \kappa), \tag{2.12}$$

When κ is an arbitrary constant and B_m, w, λ, μ are constants to be determined later, $B_m \neq 0$. For the value of m , we consider the homogeneous balance between highest order derivatives and non-linear terms appearing in Eq. (2.3).

Step 4. Inserting Eq. (2.4) into Eq. (2.3) along with Eq. (3) and Eq. (4), then we get a polynomial of $\exp(-\Phi(\xi))$. Then setting all the coefficients of

same power of $\exp(-\Phi(\xi))$ to be zero, we obtain a set of PDEs with respect to B_m, w, λ and μ . By solving the PDEs using symbolic calculation Maple, we get some explicit expression of B_m, w, λ and μ . Substituting the values of B_m, w, λ, μ into Eq. (2.4) along with general solutions of Eq. (2.5) completes the determination of the solution of Eq. (2.1).

III. APPLICATION

In this section, we will apply the $\exp(-\Phi(\xi))$ -expansion method to construct abundant exact solution of an integrable (2+1)-dimensional generalized Hirota- Satsuma equation[13],

$$3(u_x u_t)_x + u_{xxx} + u_{yt} + u_{xx} = 0, \tag{3.1}$$

where $u(x, y, t)$ is the amplitude of the relevant wave mode.

Consider the traveling wave transformation

$$u = u(x, y, t), \xi = x + y - wt, u = u(\xi), u(x, y, t) = u(\xi). \tag{3.2}$$

Inserting Eq. (3.2) into Eq. (3.1), then we get the following ordinary differential equation:

$$(1-w)u'' - 6wu'u'' - wu'''' = 0. \tag{3.3}$$

Integrating with respect to ξ , we obtain the following ODE

$$V + (1-w)u' - 3w(u')^2 - wu''' = 0 \tag{3.4}$$

Balancing the highest order derivative u''' and non-linear term $(u')^2$, we get $2(m+1) = m+3$, which gives $m=1$. Hence Eq. (2.4) becomes

$$u(\xi) = a_0 + a_1 \exp(-\phi(\xi)). \tag{3.5}$$

where a_0 and a_1 are constants to be determined later such that $a_1 \neq 0$ while λ and μ are arbitrary constants.

$$u' = -a_1(e^{-\phi(\xi)}\lambda + e^{-2\phi(\xi)} + u) \tag{3.6}$$

$$u'' = a_1(e^{-\phi(\xi)}\lambda^2 + 3e^{-2\phi(\xi)}\lambda + 2e^{-\phi(\xi)}\mu + \lambda\mu + 2e^{-3\phi(\xi)}) \tag{3.7}$$

$$u''' = -a_1 \left(e^{-\phi(\xi)}\lambda^3 + 7e^{-2\phi(\xi)}\lambda^2 + 8e^{-\phi(\xi)}\lambda\mu + \lambda^2 u + 8e^{-2\phi(\xi)}u + 12e^{-3\phi(\xi)}\lambda + 2u^2 + 6e^{-4\phi(\xi)} \right) \tag{3.8}$$

Substituting u, u', u'' and u''' into Eq. (3.4) and then equating the coefficients of $\exp(-\Phi(\xi))$ to zero, we get a set of equations as follows:

$$-3wa_1^2 + 6wa_1 = 0 \tag{3.9}$$

$$-6\lambda wa_1^2 + 12\lambda wa_1 = 0 \tag{3.10}$$

$$-3\lambda^2 wa_1^2 + 7\lambda^2 wa_1 - 6\mu wa_1^2 + 8\mu wa_1 + wa_1 - a_1 = 0 \tag{3.11}$$

$$\lambda^3 wa_1 - 6\lambda\mu wa_1^2 + 8\lambda\mu wa_1 + \lambda wa_1 - \lambda a_1 = 0 \tag{3.12}$$

$$\lambda^2 \mu wa_1 - 3\mu^2 wa_1^2 + 2\mu^2 wa_1 + \mu wa_1 - \mu a_1 + V = 0 \tag{3.13}$$

Solving Eq. (3.9)–Eq. (3.13) by Maple, we get

$$V = 0, w = \frac{1}{\lambda^2 - 4\mu + 1}, a_0 = a_0, a_1 = 2. \tag{3.14}$$

Where λ and μ are arbitrary constants.

Inserting Eq. (2.6)-Eq. (2.12) with Eq. (3.14) into Eq. (3.5) respectively, we get the following seven traveling wave solutions of the gHS equation.

When $\lambda^2 - 4\mu > 0, \mu \neq 0$,

$$u_1 = a_0 + \frac{4\mu}{-\sqrt{\lambda^2 - 4\mu} \tanh\left(\frac{1}{2}\sqrt{\lambda^2 - 4\mu}(\xi + k)\right) - \lambda}, \tag{3.15}$$

$$u_2 = a_0 + \frac{4\mu}{-\sqrt{\lambda^2 - 4\mu} \coth\left(\frac{1}{2}\sqrt{\lambda^2 - 4\mu}(\xi + k)\right) - \lambda}, \tag{3.16}$$

$\xi = -\frac{t}{\lambda^2 - 4\mu + 1} + x + y$, where k is an arbitrary constant.

When $\lambda^2 - 4\mu < 0, \mu \neq 0$,

$$u_3 = a_0 + \frac{4\mu}{\sqrt{-\lambda^2 + 4\mu} \tan\left(\frac{1}{2}\sqrt{-\lambda^2 + 4\mu}(\xi + k)\right) - \lambda}, \tag{3.17}$$

$$u_4 = a_0 + \frac{4\mu}{\sqrt{-\lambda^2 + 4\mu} \cot\left(\frac{1}{2}\sqrt{-\lambda^2 + 4\mu}(\xi + k)\right) - \lambda}, \tag{3.18}$$

$\xi = -\frac{t}{\lambda^2 - 4\mu + 1} + x + y$, where k is an arbitrary constant.

When $\lambda^2 - 4\mu = 0, \mu = 0, \lambda \neq 0$

$$u_5 = a_0 + \frac{2\lambda}{e^{\lambda(\xi+k)} - 1}, \tag{3.19}$$

$\xi = -\frac{t}{\lambda^2 + 1} + x + y$, where k is an arbitrary constant.

When $\lambda^2 - 4\mu > 0, \mu \neq 0, \lambda \neq 0$

$$u_6 = a_0 - \frac{\lambda\left(-\frac{t}{\lambda^2 - 4\mu + 1} + x + y + k\right)^2}{\lambda\left(-\frac{t}{\lambda^2 - 4\mu + 1} + x + y + k\right) + 2}, \tag{3.20}$$

where k is an arbitrary constant.

When $\lambda^2 - 4\mu = 0, \mu = 0, \lambda = 0$

$$u_7 = a_0 + \frac{2}{-\frac{t}{\lambda^2 - 4\mu + 1} + x + y + k}, \tag{3.21}$$

where k is an arbitrary constant.

IV. GRAPHICAL REPRESENTATION

In this subsection, we will discuss the graphical representation of some obtained solution of an integrable (2+1)-D generalized Hirota- Satsuma equation. By applying the $\exp(-\Phi(\xi))$ -expansion method to above equation, we get some solutions which are $u_1(x, y, t), u_2(x, y, t), u_3(x, y, t), u_4(x, y, t), u_5(x, y, t), u_6(x, y, t)$ and $u_7(x, y, t)$. Here, we plotted three types solution among seven, first is exact kinky type solitary wave, second is periodic kinky type solitary wave and third is periodic line breather wave solution, which are display in Fig.1-Fig.3, respectively.

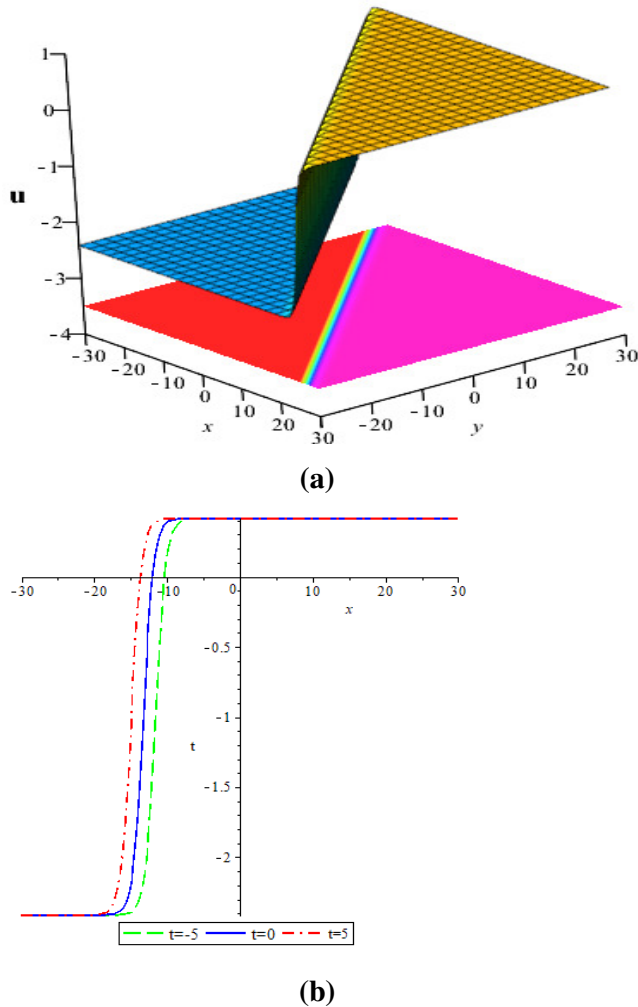


Fig.1. Kink type soliton profile of Eq. (3.1) for $\lambda = 2, \mu = 0.5, a_0 = 1, E = 2$ of u_1 . (a) Top shows the 3D plot and bottom is corresponding density plot. (b) Shows the 2D plot for different value of t .

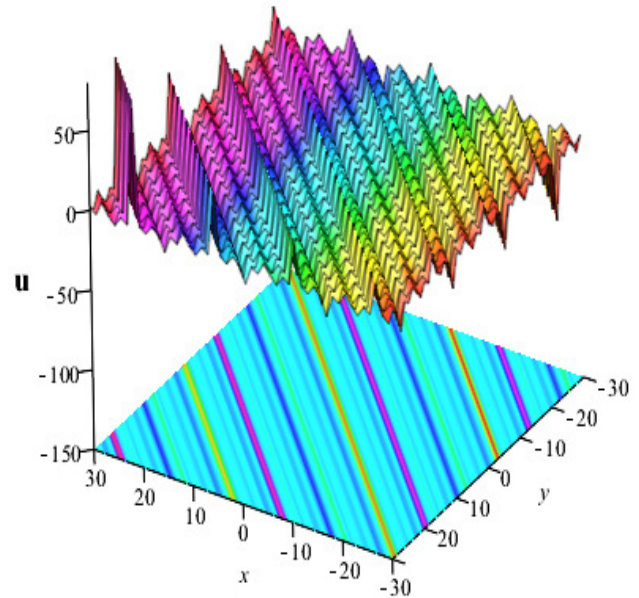
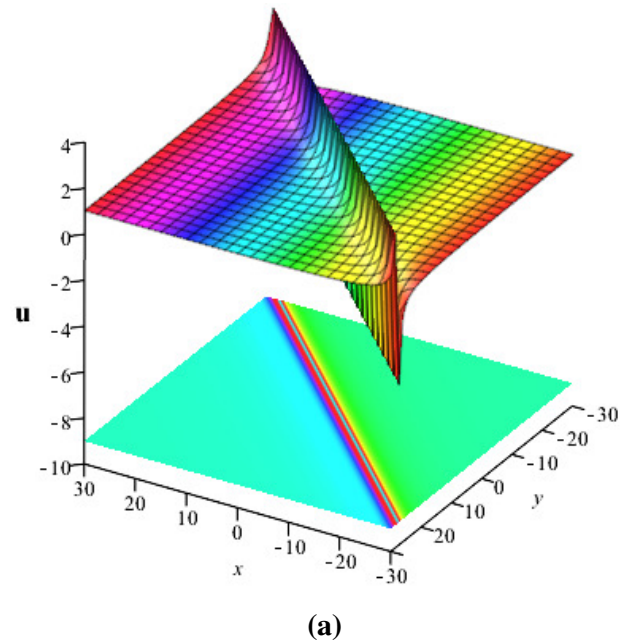


Fig.2. Periodic wave profile of Eq. (3.1) for $\lambda = 0.5, \mu = 1, a_0 = 1, E = 2$ of u_4 , top shows the 3D plot and bottom is corresponding density plot.



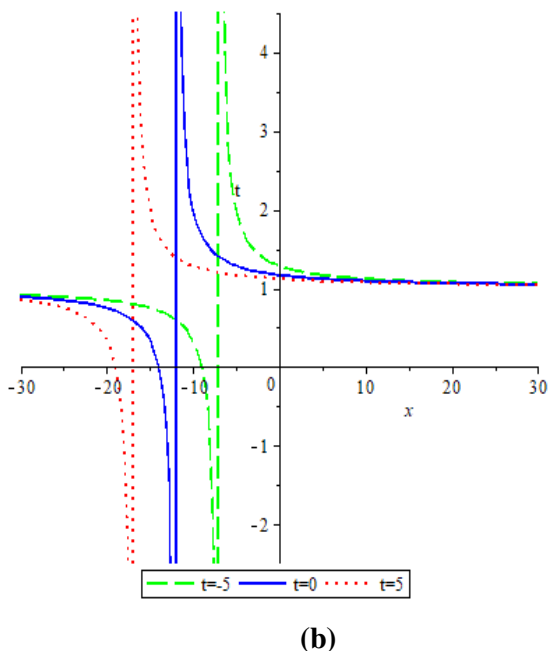


Fig.3. Periodic line breather wave profile of Eq. (3.1) for $\lambda = 0, \mu = 0, a_0 = 1, E = 2$ of u_7 . (a) Top shows the 3D plot and bottom is corresponding density plot. (b) Shows the 2D plot for different value of t .

V. CONCLUSIONS

In summary, based on the $\exp(-\Phi(\xi))$ -expansion method and by a symbolic computation, we obtain some exact solutions of an integrable (2+1)-dimensional generalized Hirota- Satsuma equation such as trigonometric, hyperbolic and breather type solution. Some of them are graphically illustrated which are shown in Fig.1 to Fig.3. We hope that presented results are very much helpful in the field of science and engineering.

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