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# Transversal hypersurfaces in pseudo-Riemannian manifolds

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## Abstract:

In this paper we derive a condition of transversality of two given hypersurfaces in pseudo-Riemnnaian manifolds, along its boundary. This condition is given by the ellipticcity of the Newton transformations.

*Keywords* —Newton transformations, Symmetric functions, Transversality.

### I. PRELIMINARIES

In this section we will recall basic formulas and notions about hypersurfaces in pseudo-Riemannian space forms that will be used later on.For more details see [7].

Let  $M^{n+1}$  an (n+1) dimensional pseudo-Riemannian manifold of index  $q \ge 0$  and let  $M^n$  be a nondegenerate oriented hypersurface of  $M^{n+1}$ . If we denote by A the corresponding shape operator, then at each  $p \in M^n$ , A restrict stoaself-adjoint linear map

 $A_p: T_pM \to T_pM.$ 

Associated to  $A_p$  there are *n* algebraic invariants defined by

 $S_r = \sigma_r(x_1(p), \dots, x_n(p)).$ 

Where

$$\sigma_r: \mathbb{R}^n \to \mathbb{R}^n$$
,

are the elementary symmetric functions and

 $x_1(p),...,x_n(p)$  are the pricipale curvature of the hypersurface.

For  $0 \le r \le n$ , we define the  $r^{th}$  mean curvature of the hypersurface by

$$\binom{n}{r}H_r = \varepsilon_N^r S_r = \sigma_r(\varepsilon_N x_1, \dots, \varepsilon_N x_n).$$

Observe that  $H_0 = 0$  and  $H_1 = \frac{1}{n} traceA$  is the usual mean curvature of M which is one of the most important extrinsic curvatures of the hypersurface.

Let  $\chi(M)$  be the space of vector fields on the manifold M. The classical Newton transformations associated to the shape operator A are defined inductively by

$$\begin{cases} T_0 = 0, \\ T_r = \varepsilon_N^r S_r - \varepsilon_N^{r-1} A T_{r-1} forr \ge 1. \end{cases}$$

Or equivalently by

$$T_r = \varepsilon_N^r S_r - \varepsilon_N^{r-1} S_r A + \dots + (-1)^r A^r.$$

where *I* is the identity maps  $in\chi(M)$ .

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Observe that the operator  $T_r$  is self-adjoint and commutes with A. Therefore all basis of  $T_pM$  that diagonalizing A at pdiaginalizes all of the  $T_r$ . Let  $\{e_1, \dots, e_n\}$  such basis.

Denoting by  $A_i$  the restriction of Ato  $\langle e_i \rangle^{\perp}$ . It is well know that :

$$\det(tI - A_i) = \sum_{r=0}^{n-1} (-1)^r S_r(A_i) t^{n-1-r}.$$

Where

$$S_r(A_i) = \sum_{\substack{i_1 < \cdots < i_r \\ i_i \neq i}} x_{i_1} \cdots x_{i_r}.$$

It is immediate to check that

$$T_r e_i = \varepsilon_N^r S_r(A_i) e_i.$$

We refer the reader to [2] and [7] for other details about classical Newton tensors for hypersurfaces in Riemannian and pseuo Riemannian spaces.

#### II. GENERALIZED NEWTON TRANSFORMATIONSS

Let *E* be an n-dimensional real vector space and End(E) be the vector space of endomorphisms of *E*. Denote by  $\mathbb{N}$  the set of nonnegative integers and let  $\mathbb{N}^2$  be the one of multiindex $u = (u_1; u_2)$ , with  $u_i \in \mathbb{N}$ . The length |u| of *u* is given by  $|u| = u_1 + u_2$ . Fo $A = (A_1; A_2) \in End(E) \times End(E)$ ,  $t = (t_1; t_2) \in \mathbb{R}^2$  and  $u \in \mathbb{N}^2$ , we set  $tA = t_1A_1 + t_2A_2$ ,  $t^u = t_1^{u_1} \cdot t_2^{u_2}$ .

The generalized Newton transformations (GNT in brief ) is a system of endomorphisms

$$T_u=T_u(A_1;\,A_2),\ u\in\mathbb{N}^2$$

that satisfies the following recursive relations [4]

$$\begin{split} T_{(0,0)} &= 0, \\ T_{(i,j)} &= \sigma_{(i,j)} I - A_1 T_{(i-1,j)} - A_2 T_{(i,j-1)} \end{split},$$

if
$$i + j \ge 1$$

Where  $\sigma_{(i,j)}$  are the coeccients of the Newton polynomial

 $P_A: \mathbb{R}^q \longrightarrow \mathbb{R}$ 

of A given by

$$P_A(t) = \det(I + t_1 A_1 + t_2 A_2)$$
$$= \sum_{i+j < n} \sigma_{(i,j)} t_1^{i} t_2^{j}$$

#### III. MAIN RESULTS

Let  $M^{n+1} \alpha v (v + 1)$  dimentional connected pseudo-Riemannian manifold of index  $\theta$ , and  $\varphi: M^n \longrightarrow M^{n+1}$  be an oriented connected hypersurface of  $M^{n+1}$  with smooth boundary  $\cong M$ . Assume the boundary  $\Sigma = \varphi(\partial M)$  is a one codimensionsubmanifold of an oriented connected hypersurfaces $P^n \subset M^{n+1}$ .

Consider the second fundamental operators,  $A_{\Sigma}$ ,  $A^{\zeta}$  and  $A^N$  corresponding to the inclusions  $\Sigma \subset P^n$ ,  $P^n \subset M^{n+1}$ ,  $M^n \subset M^{n+1}$  respectively.

Where  $\zeta$  and N are the unit normal vector fields of the inclusions  $P^n \subset M^{n+1}$  and  $M^n \subset M^{n+1}$  respectivly

Following [2] we consider a local orthogonal frame  $\{e_1, \dots, e_{n-1}\}$  in  $\Sigma$ ,  $\nu$  the out pointing conormal unit vector field of  $\Sigma$  and  $\eta$  the unitary vectorfield normal to  $\Sigma$  in  $P^n$ .

We have

$$\overline{\nabla}_{e_i} e_j = \sum_{k=0}^{n-1} \varepsilon_k \langle \overline{\nabla}_{e_i} e_j, e_k \rangle e_k + \varepsilon_\nu \langle \overline{\nabla}_{e_i} e_j, \nu \rangle \nu + \varepsilon_N \langle A^N e_i, e_j \rangle N.$$

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And

$$\overline{\nabla}_{e_i} e_j = \sum_{k=0}^{n-1} \varepsilon_k \langle \overline{\nabla}_{e_i} e_j, e_k \rangle e_k + \varepsilon_\eta \langle A_{\Sigma} e_i, e_j \rangle \eta + \varepsilon_{\zeta} \langle A^{\zeta} e_i, e_j \rangle \zeta.$$

Thus

$$\varepsilon_{\nu} \langle \overline{\nabla}_{e_i} e_j, \nu \rangle \nu + \varepsilon_N \langle A^N e_i, e_j \rangle N$$
  
=  $\varepsilon_{\eta} \langle A_{\Sigma} e_i, e_j \rangle \eta + \varepsilon_{\zeta} \langle A_{P} e_i, e_j \rangle \zeta.$ 

Hence

$$\begin{split} \langle A^N e_i, e_j \rangle &= \varepsilon_\eta \langle A_\Sigma e_i, e_j \rangle \langle \eta, N \rangle \\ &+ \varepsilon_\zeta \langle A_{\rm P} e_i, e_j \rangle \langle \zeta, N \rangle. \end{split}$$

Suppose that  $P^n$  is totally umbilic, so there exist a smooth function $\lambda$  such that

 $A_{\rm P} = \lambda I_{n-1},$  and we have

$$A\Big|_{\Sigma} = \rho A_{\Sigma} + \mu \langle \zeta, N \rangle I_{n-1}.$$

This formula shows that the geometry of the inclusion  $\Sigma \subset P^n$  is codded by the couple  $(A_{\Sigma}, I_{n-1})$ , and the geometry of the inclusion  $M^n \subset M^{n+1}$  is given by *A*.

We will use the Newton trasformations and the generalized Newton transformations :

$$T_{\mathrm{r}} = T_{\mathrm{r}}\left(A \mid_{\Sigma}\right) and T_{k,l} = T_{k,l}(A_{\Sigma}, I_{n-1}).$$

and the correspondaingelementary symmetric functions

$$\sigma_{\mathrm{r}}\left(A\mid_{\Sigma}\right)$$
 and  $\sigma_{k,l}(A_{\Sigma}, I_{n-1})$ .

In this case we have

$$\sigma_{\rm r}\left(A\left|_{\Sigma}\right) = \sum_{k+l=r} \rho^l . \, \mu^k \sigma_{k,l}$$

And

$$\langle T_{\rm r}\nu,\nu\rangle = \sum_{k+l=r} \rho^l.\,\mu^k\sigma_{k,l}$$

The matrix *A* is writing in the basis  $\{e_1, \dots, e_{n-1}, \nu\}$ 

$$\begin{pmatrix} \gamma_1 & 0 & \dots & \varepsilon_1 \langle A\nu, e_1 \rangle \\ 0 & \gamma_2 & \dots & \vdots \\ & & \gamma_{n-1} & \varepsilon_{n-1} \langle A\nu, e_{n-1} \rangle \\ \varepsilon_1 \langle A\nu, e_1 \rangle & \dots & \varepsilon_{n-1} \langle A\nu, e_{n-1} \rangle & \varepsilon_{\nu} \langle A\nu, \nu \rangle \end{pmatrix}$$

Puting

$$A = \begin{pmatrix} A \mid \Sigma & B \\ B^T & c \end{pmatrix}.$$

Where,

$$B = \begin{pmatrix} \varepsilon_1 \langle A\nu, e_1 \rangle \\ \vdots \\ \varepsilon_{n-1} \langle A\nu, e_{n-1} \rangle \end{pmatrix},$$

and

$$c = \varepsilon_{\nu} \langle A\nu, \nu \rangle.$$
  
We have the following results.

#### Proposition 1.

Let  $M^{n+1}$  an (n + 1) pseudo-Riemannian manifold, and  $P^n$  a totally umbilical hypersurface of  $M^{n+1}$ . Denoting by  $\Sigma \subset P^n$  a compacthypersurfaceof  $P^n$ . Let  $\varphi: M^n \longrightarrow M^{n+1}$  be an oriented connected hypersurfaceof  $M^{n+1}$  with boundary  $\Sigma = \varphi(\partial M)$ . Then along the boundary  $\Sigma$ , we have

$$\langle T_{\mathbf{r}}\nu,\nu\rangle=\sigma_{\mathbf{r}}\left(A\mid_{\Sigma}\right).$$

#### Theorem1.

Under the above hypothesis,  $M^n$  and  $P^n$  are transversealong  $\Sigma$  if for some  $1 \le r \le n$  the Newton transformation  $T_r$  is positif defined.

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