

REVIEW OF THEORY OF BALANCING OF ROTATING MASSES.

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ABSTRACT:

When the rotor rotates, the centrifugal inertia force exists because the part has the eccentric mass, and the eccentric mass is not on the axis of rotation. That is means that the mass diameter product is not zero. Since balancing is generally carried out on both sides of the balance, the balance mass can be decomposed into two sections offset from the center of mass and perpendicular to the axis of rotation. Simple geometry and multiple applications such as drying, mixing, segregation and heat conduction have inspired many researchers from the mechanical, chemical, pharmaceutical and mining engineering fields to study the dynamics of the particle flow inside rotating drums. This paper has critically reviewed the phenomenon of Balancing of rotating masses and intensive critical review of the literature is being done on this area.

KEYWORDS: Rotating-masses, balancing, Angular-velocity.

S.K.Trehan [1] used first variations of the integral properties of equilibrium second-order virial relations to demonstrate the existence of the point of bifurcation of rotating gaseous masses with magnetic fields. The presence of a magnetic field component along the axis of rotation alters the point of bifurcation, where the Jacobi ellipsoids branch off from the Maclaurin spheroids, and shifts to higher eccentricity values than the one obtained when there is no magnetic field (namely, $e = 0.81267$). S.T. Chiou [2] investigated the two-Rotating-mass balancers for Partial Spatial Mechanisms Balancing. The k th frequency term of the shaking force and shaking moment of high-speed spatial mechanisms can be represented by two force vectors of constant magnitude but generally unequal magnitude rotating at k time's cycle frequency. Equal and opposite forces with the same locations as those exerted by counterweights mounted on shafts rotating at the same speed can be used to eliminate the forces. As a result, the k th frequency term of the shaking force and moment can be balanced. Two-rotating-mass balancers are the counterweights. It is also demonstrated that the derived formulae can be specialized for the design of generalized Lanchester balancers for partial balancing of planar mechanisms. An example of a seven link 7-R spatial linkage is given to demonstrate the theory and the balancing effects of the two-rotating-mass balancers. Chiou and Davies and Davies and Niu [4] provided discussions on the benefits and drawbacks of using rotating mass balancers. One advantage of using constant angular velocity balance masses is that if a flywheel is used to limit speed fluctuations and the shaft rotating at constant speed is mechanically coupled to the flywheel, the additional inertia of that shaft will reduce the flywheel inertia required. However,

if a brake is used to provide emergency stops, a mechanically coupled shaft with increased inertia will necessitate a greater braking torque. Extra shafts and their drives add weight and cost to the overall package. As a result, it is preferable to mount counterweights on any suitable shaft that is required for other purposes. A shaft of this type must rotate at crank speed or a multiple of k of crank speed, where k is an integer. It may be difficult to find space for a drive from existing shafts, and even if space is available, it may be difficult to install. It is simpler to incorporate an encoder into an existing machine. Any additional installations can then be powered by independent electric drives that are synchronized with the encoder via electronic gearing. [2] Sarkadi, Dezs, in his paper, he provides a detailed account of a previously unknown manifestation of gravity. There is a lot of talk about gravity in today's physics, especially when it comes to the universe (the expanding universe, dark energy and dark mass, etc.). Another frequently mentioned issue is the lack of a quantum theory of gravity, which is closely related to the fact that the widely accepted peak theory, the Standard Model, does not include gravity. In today's physics, theory has come to the fore, and the role of experiments, particularly high-energy particle accelerators, has been reduced to proving peak theory. The gravitational interaction (force) depends only on the size and distance of the interacting masses, not on their motion, according to Newtonian gravity's well-known law. In Hungary, a previously unknown gravitational phenomenon, namely the strong gravitational effect between accelerating masses, was discovered. The Hungarian experimentation clearly demonstrated that the gravitational force occurring between

artificially moved masses can be orders of magnitude stronger than Newtonian gravity. Furthermore, depending on the relative motion of the interactive masses, gravitational repulsion could be observed in addition to attraction. The new recognition resulted in the phenomenon and concept of dynamic gravity being introduced. Dynamic gravity theory complements Newtonian static gravity in the same way that electrostatics complements static electricity. The classical physics symmetries that apply to Newton's law of gravity (conservation of energy, linear and angular momentum, invariance of space-time mirroring) also apply to dynamic gravity. Because of its simplicity, speed, and visibility, the gravitational experiment described in this work is suitable for a simple demonstration of gravity even at the elementary school level. At the moment, the Cavendish experiment is being presented. [3]

Lieutenant G. Eberhart believed that the majority of operating engineers did not fully comprehend the concept of rotating mass balancing. The art of balancing is relatively new, and many people mistakenly believe that it is too complicated for anyone other than a "expert" to understand. Others, while not understanding its underlying principles, are aware of the existence of the art and conclude that if balancing is required in some cases, it must be required in all cases. As a result, on the one hand, unbalance is ignored, while on the other, it is assumed to be the evil in hence that causes all real or imagined vibration. When this latter viewpoint is taken, work requests are submitted to balance this, that, or whatever, with no real understanding of the necessity, of the relative cost, or of the fact that, aside from handling and rigging charges, it costs the same to balance a small object as it does a large one. Weiqiang Zheng, Chengjie Rui, Jie Yang and Pingyi Liu[5] in their paper wrote, Due to the design and processing technology of rotary shaft, the mass center of it does not coincide with the rotating axis of the rotary shaft and there is an unbalanced mass. The unbalanced mass can have some disadvantages, such as the centrifugal force, the vibration and so on. Those disadvantages could reduce the accuracy and service life of the equipment. In this paper, the dynamic balance of the rotary shaft is analyzed by the theory analysis combined with the dynamic simulation software. This method ensures that the rotary shaft meets the dynamic balancing requirements during the design stage. It effectively supports the structural design of the rotary shaft, and provides a way of thinking and method for the design and development of the same type of products. (1) In this paper, theoretical analysis combined with dynamic simulation software is used in the product design of the dynamic balance of crankshaft virtual test, effectively support the structure of the crankshaft design, and provides a design method for the same type of product, the authors concluded. (2) The magnitude of the residual unbalance in section 1 is $0.00368 \text{ g} \cdot \text{mm}$, the magnitude of the residual unbalance in section 2 is $0.00111 \text{ g} \cdot \text{mm}$, and the overall balance accuracy is $0.02176 \text{ mm} / \text{s}$ after the crankshaft is dynamically balanced using this method, and

the result meets the design requirements. Jacek Uziak[6] describe the use of teaching aids in the teaching of rotating mass balancing. The goal was to provide the student with a three-dimensional visualization of the topic, allowing them to gain a thorough understanding of the problem. As their final year project, final-year students of a Bachelor of Engineering (mechanical) programmed designed and developed the aids. The aids came in the form of both a physical and a virtual model. The physical model was a toy-like structure that demonstrated key aspects of the topic, while the virtual model compared a balanced rotating shaft to an out-of-balance rotating shaft. To assist students, an Excel workbook and a MATLAB programmer were created. The aids were tested in the Mechanics of Machines class, and the results showed that they were effective. In this article, the authors describe the use of teaching aids to provide insight into the topic of balancing rotating masses. The main goal was to provide students with a three-dimensional visualization of the topic, allowing them to gain a thorough understanding of the problem. A mechanical toy-like model, a virtual model in the form of a video clip, a spreadsheet, and a MATLAB programmer were developed to help students check their manual calculations. According to P. Widhate[7] various experimental and numerical studies have been conducted to study the velocity profiles of particles inside horizontal rotating drums, but little emphasis has been placed on inclined rotating drums, despite the fact that these drums are widely used in granular process industries.

The discrete element method was used to investigate the velocity profiles of particles in a rotating drum with inclinations of 0° , 5° , 10° , and 15° in this study. The inclined rotating drum has a similar variation of velocity with radial height to the horizontal rotating drum at locations of the drum with volumetric fill in the range of 0.2 - 0.8. The variation of the average particle velocity along the length of the drum, on the other hand, differs between horizontal and inclined drums. Furthermore, for the inclined rotating drum, the average velocity increases as the volumetric fill increases. DEM simulations with an inclined rotating drum were performed in this study for 0° , 5° , 10° , and 15° angles of inclination. The profiles of velocity in the bed surface direction along the radial height for the inclined rotating drum are similar to that of the horizontal rotating drum in the cross section of the drum with volumetric fill in the range of 0.2 - 0.8. However, the variations in average particle velocity along the length of the drum differ when inclined and horizontal rotating drums are compared. The average velocity of the horizontal drum is almost constant along its length, whereas the inclined drum's average velocity is almost constant in the lower part of the drum and decreases with length in the upper part. When all angles of inclination are considered, the average particle velocity increases as the volumetric fill increases. In their article, Pulsed laser ablation as a tool for in-situ balancing of rotating, M. Stoesslein, D. A. Axinite*, and A. Guillerna[8] A laser balancing system is

being developed for parts in order to continuously remove material from a target part in a controlled and automated manner. An influence coefficient that is related to the change in vibration amplitude for a predefined number of pulses at a given operational balancing speed, material, and geometry of the rotative part can be used to control the amount of material ablated. In a fully automated system, the proposed system uses a three-layered case-driven programmatic approach to optimize single-plane balancing process duration. Prioritization can thus be used to avoid misfire and, as a result, structural damage to the targeted part. Furthermore, the application enables the component to be balanced to any of the ISO 1940/1 balancing grades. Thus, the validation trials entailed balancing an Inconel 718 rotative to a preliminarily specified balancing grade by extracting acceleration signals with an IIR peak filter. To validate the trials, a computer simulation encompassing the rotor bearing state space system, a laser model, and the adapted peak detection algorithm was developed and used. A maximum deviation from the desired correction position of less than 1 mm will now be recorded. Furthermore, it has been demonstrated that reducing the vibration level of a rotor from G 22.5 to G 19.5 can reliably detect and correct imbalances. Wang, C.Y. [9] Condensation film on a rotating inclined disc, Applied Mathematical Modelling 31 (2007) 1582–1593, the similarity transform is used to solve the three-dimensional problem of steady fluid deposition on an inclined rotating disc. There may be one, two, or no steady state solutions for a given spraying rate. Because of the inclination, there is a downward draining flow as well as a lateral flow. When the fluid film is thin, perturbation solutions outperform exact similarity solutions. [9]

Conclusion

The intensive literature review finds that there is scope to work on the balancing of rotating masses. The Two-Rotating-Mass Balancers are sufficient for Partial Spatial Mechanisms Balancing. One advantage of using constant angular velocity balance masses is that if a flywheel is used to limit speed fluctuations and the shaft rotating at constant speed is

mechanically coupled to the flywheel, the additional inertia of that shaft will reduce the flywheel inertia required. Various experimental and numerical studies need to be conducted to study the velocity profiles of particles inside horizontal rotating drums, but little emphasis has been placed on inclined rotating drums, despite the fact that these drums are widely used in granular process industries. The discrete element method can be used to investigate the velocity profiles of particles in a rotating shaft with inclinations of masses.

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